2.7 Mapping Scan



PARIPod: 2.7 Mapping Scan

The PARIPod is **4:44** min in length.



Presentation Slide 2.7



Student Guide: P.11



Quiz 2.7

Starting Point

- 1. A mapping scan is basically several <u>spectrum snapshots</u> put together over a source to form a larger map. This is like taking many small photos of an object put together to make a larger one.
- **2.** Set Smiley to target an object.
- **3.** Go to the Mapping Scan tab at the bottom.
- **4.** Use default parameters unless the lab or your instructor tells you otherwise.
- **5.** The scan controls and parameters of a mapping scan are the same as the other scans except there are now two new controls, AZ (Azimuth) and Altitude (ALT). These two controls help guide the speed thus the <u>sampling rate</u> while Smiley zigzags around its target area.
- **6.** A lower rate <u>increases</u> the accuracy of the scan and a higher rate <u>decreases</u>.
- 7. The scanning range controls the size of the target range. The larger the range, the larger the grid, or map. The X-axis is the Azimuth while the Y axis is the Altitude.
- **8.** <u>Delta</u> shows the current scan positioning.
- 9. To start your mapping scan, click Begin Scan, Smiley will begin taking data. There will be a 20 second delay before data begins being plotted on the graph, which allows smiley to position itself towards the target. Plots on your graph appear as square grayscale patches. This creates a mosaic map, which is a composite image of the target. Analyze or rescan data according to variations in your map. Depending on the variation in your graph, you may want to rescan with a higher IF gain.
- **10.** The Scan will *automatically* stop once it has scanned the set map area or you can hit Stop Scan to stop the data collection.
- 11. Useful Scan data file should be *saved*.
- **12.** Once scanned, refer to Analyzing Smiley Data (PARIPod 2.8)

Proceed to 2.8